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HIGH LEVEL Vis-IR STIMULATED NVG TRAINING

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ABSTRACT

Physically accurate Night Vision training for flight simulation is provided by combining standard issue NV goggles, a VITAL X image generator and database, and the AVIOR[®]VisIR laser projection system.

The AVIOR[®]VisIR projector contains an IR laser that overlays an independent infrared image onto the out-thewindow scene drawn by an RGB laser. The RGB laser provides a high-contrast scene optimized for unaided viewing while the IR laser provides a physically accurate stimulation of standard issue Night Vision Goggles (NVG). The visible and infrared projections can be driven from independent IG channels without sacrificing physical accuracy in either projection. As a cost saving option, a single IG channel can drive both projections via one of two "clone" transform techniques without significantly sacrificing physical realism. These clone operating modes are features of the AVIOR[®]VisIR projector.

VITAL X's physics-based display system model takes into account real-world radiances, projector spectral and dynamic behavior, as well as spectral and dynamic responses of the NVGs. As a result, deterministic integration of the high contrast AVIOR[®]VisIR laser projector with different goggle types is straightforward.

INTRODUCTION

The us e o f night vi sion g oggles i s b ecoming more important f or b oth military o perations a nd c ivilian missions. In m ilitary operations, the night o ffers protection from visual d etection by h ostile f orces; however, visual r econnaissance i s al so considerably limited. For this reason, operational forces have long been using night v ision devices t o en hance t heir visual perception. A s p assive s ensors, a mbient light i intensifiers offer t he opt imum c apability f or n ight v ision de vices – "seeing w ithout being s een" – without t he ne ed for additional illu mination. For civilian missions, especially rotary wing ones, the situational a wareness provided by using NVGs increases safety in d ense urban areas and unfamiliar, close contact environments.

However, the effective use of night vision goggles requires thorough training. Their special characteristics d emand a specific set of skills be developed. Night vision go ggles have a na rrow field of v iew s howing monochromatic, grainy images with limited resolution. NVGs also exhibit effects s uch as h aloing, s mearing, and blooming around bright light sources. This is why intensive NVG training is important in assuring the overall success of the mission. Simulators o ffer an s afe e nvironment t o a ccomplish this before the pilots or soldiers encounter these often extreme situations in life threatening situations.

NIGHT VISION TRAINING IN SIMULATORS

Night vi sion t raining i n s imulators c an b e accomplished using two basic methods. Pilots can either be trained with simulated go ggles o r the display s ystem can s timulate standard issue goggles.

Night vision training with simulated goggles replicate standard issue NVGs by building in small displays in place of t he light i ntensifier t ubes. The N V i mage i s then generated by a d edicated I G channel that m ust ha ve a sophisticated model for h ow each type of goggles reacts under specific p hysical stimuli. Additionally, p ilots must wear a head tracking system in o rder t o g enerate the appropriate view within the IG.

Simulated goggles also incur a dditional d isadvantages. The cockpit structure, instruments, and lighting can not be observed through simulated goggles. All such information must be replicated virtually within the IG. Pilots typically complain a bout g oggle and h ead t racker discomfort, a s well as about the shortcomings of the cockpit simulation and overall N VG r ealism compared to th eir o riginal equipment.

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In c ontrast, o ptimum tr aining with high r ealism c an b e achieved when the trainee is able to use his own original night vision goggles in the simulator. The actual goggles are "stimulated" by the out-the-window display. It is important that the projectors used have a good black level in order to provide good night scene realism.

Traditional out-the-window projectors have limited energy in the NVG p assband. As a r esult, the i mage typically needs to be color shifted with a r ed c ast to sufficiently stimulate NVGs. Therefore night scenes observed with the naked eye may be reddish or even too bright. In addition to the red cast, the stimulated NV image may show a limited dynamic range and lack of NV effects like halos or blooming.

To o vercome t his o bstacle, the AV IOR[®]VisIR 1 aser projection system overlays two images as on the screen 1) a visible dark night scene and 2) an infrared image, which effectively stimulates t he g oggles b ut i s i nvisible to th e naked eye. As a result, the visible and NVG images can be independently controlled, and the proper balance of visible and NVG stimulation can be achieved (Reference 1).

The AVIOR[®]VisIR projection system has been integrated with a variety of Image Generators. A particularly good combination is the AVIOR[®]VisIR c oupled with the FlightSafety VI TAL X I G. The V ITAL X p rovides a traceable real-world illumination model and physics-based rendering, which are used to advantage in controlling the AVIOR[®]VisIR's inherent ability to properly stimulate the NVGs. See Reference 2.

AVIOR®VisIR LASER PROJECTION

The AVIOR[®]VisIR laser projection basically consists of a laser s ource that generates a laser b eam. T his b eam is intensity-modulated with t he v ideo s ignal a nd t hen transferred via an optical fiber to a projection head where a two-axis scanner d eflects t he modulated laser b eam i n horizontal and vertical d irections, writing a n image line-by-line directly onto the screen.

In the AVIOR[®]VisIR projector, a solid-state laser oscillator g enerates r ed g reen an d b lue l aser b eams for writing the visible image onto the screen. The RBG laser beams ar e t hen ex ternally modulated via acousto-optical modulators an d r ecombined into o ne s ingle b eam. T he RGB l aser b eam i s co upled i nto t he o ptical f iber an d transferred to the projection head.

A second laser source located i nside the projection head generates t he f ourth wavelength ne ar 8 30 n m f or t he invisible IR image. A small semiconductor laser diode is directly cu rrent-modulated with the v ideo s ignal. The resulting beam is coupled into a fiber and combined with the RGB laser beam in the projection head. The projection head consists of an extremely fast rotating polygon mirror which deflects the incoming video-modulated laser beam horizontally writing a line. A second galvanometric mirror is r esponsible for the vertical d eflection retrace down t o the next line and the retrace between frames.

The two overlaid images are written onto the screen with a composite four-wavelength V is-IR l aser b eam p ixel b y pixel and line by line similar to how an electron beam in a

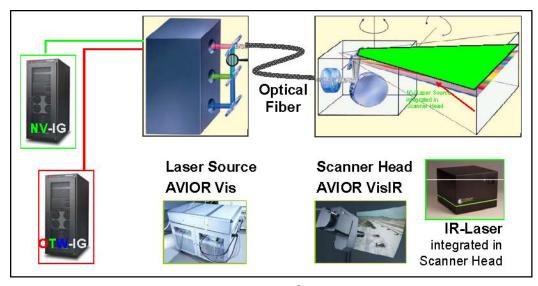


Figure 1 Principal set-up of the AVIOR[®]VisIR laser projection system.

cathode ray tube (CRT) writes an image onto a phosphor screen. The A VIOR[®]VisIR p rojector h as a UXGA resolution (1600 x 1200 pixels) with a fixed frame rate of 60 Hz.

VITAL X IMAGE GENERATOR

We s uccessfully i ntegrated t he AVIOR[®]VisIR l aser projector with the FlightSafety VITAL X image generator. VITAL X is well suited for high-quality NVG stimulation. VITAL X provides a deterministic, traceable illumination model that generates scene visual ill umination and NVG irradiance as a function of the "percent lunar illumination" and weather conditions commonly provided in pilot flight briefings. The instantaneous illumination is determined by the p ilot b riefings a ndt he c urrent e phemeris o r alternatively by the moon el evation manually en tered by VITAL X u ses h igh-dynamic r ange the in structor. rendering and dithering techniques within a floating-point CPU/GPU p ipeline to c arry th e h igh i ntrinsic d ynamic range out to the projector through 8-bit DVI video. For a given flight briefing, the night-scene view and associated NVG stimulation thus matches the real-world to the extent possible given the characteristics of the display at hand.

FlightSafety h as d eveloped an an alysist echnique for optimizing the performance of an NVG stimulation system given projector characteristics. That technique focuses on the ratio of the energy in the NVG passband to the energy stimulating n ormal unaided vision. Traditional d isplay systems generate i nsufficient N VG s timulus a nd a r ed boost i s u sually r equired t o ach ieve r easonable simultaneous aided and unaided views. See Reference 2 for details. The ratio technique assists in making optimal tradeoff de cisions be tween NVG qu ality a nd un aided scene q uality. F ortunately, the AVIOR[®]VisIR, with it s internal IR laser, can readily achieve both real-world NVG stimulation levels and real-world unaided out-the-window visual s cene ill umination with lo w b lack le vels. As a result, t he i deal s cene i llumination a nd N VG ir radiance dictated b y the V ITAL X r eal-world ill umination model can be achieved without compromise.

CLONE MODE OPERATION

The highest quality NVG stimulation is achieved when a single projector is driven by two image generator channels via t wo v ideo lin ks. O ne v ideo lin k d rives t he visible RGB l aser, and t he o ther l ink d rives t he I R l aser and i s dedicated to N VG s timulation. However, e xcellent performance can still be achieved via a single IG channel and a s ingle video link using the AVIOR[®]VisIR's "clone mode". C lone m ode operation r educes co st a nd complexity of the display system.

With clone mode operation, the IG video channel is split into two video streams within the projector. One stream connects to the V is RGB part of the AVIOR[®] laser projector, and the other stream connects to the internal IR laser. One of t het wos treams c an und ergo a programmable video transformation t hat c an be used in variety of ways to simultaneously optimize the Vis RGB display and the IR laser display as derived from the single video s ignal. Two b asic cl one mode ap proaches were evaluated during the AVIOR[®] VisIR integration with the VITAL X IG.



Figure 2 AVIOR[®]VisIR projection head writes an image generated with VITAL X image generator.

Clone Mode 1

In a f irst a lternative, the i mage g enerator g enerates t he bright I R i mage with full d ynamic r ange which i s projected by the AVIOR[®] IR l aser p rojector and which stimulates a brilliant NV i mage in the goggles with high contrast. T he v ideo s ignal for th e v isible p rojection is modified such that only the brightest parts of the image are unaffected while darker parts become increasingly darker resulting in a p rojected v isible i mage with darkened textures, dim sky and ground structures but with glistening bright artificial lights inducing halos in the NV image.

Clone M ode 1 pr ovides a go od s imultaneous match between the basic dynamic ranges of goggles and of the visible scene; however, it also requires carefully controlled tone mapping of computed light sources. "Tone mapping" is d efined as t he optimal c onversion of phy sics-model high-dynamic r ange floating point qu antities to d isplay levels that are within the capabilities of a lower-dynamic range display. Under tone mapping, a lightpoint physical brightness on the display matches that in the real-world if that b rightness is a chievable. Alternatively, if t he r ealworld brightness is not achievable, the tone mapping process produces a display value that maintains the pilot's subjective or r elative s ense of b rightness. Optimal to ne mapping c hanges with the r equested ill umination le vel. As a result, basic Clone Mode 1 operation with VITAL X tended t o h ave ar tifacts as sociated with o bjects at m idlevel b rightnesses. Clone Mode 1 i s s uitable for ba sic applications with simple, tightly controlled tone mapping; however, ope ration with f ully d ynamic t one mapping systems such as VITAL X requires that the IG tone map be dynamically co ordinated with t he p rojector's internal transformation, which is a n in teresting topic f or future integration improvements. Regardless, we achieved much better integration results using Clone Mode 2.

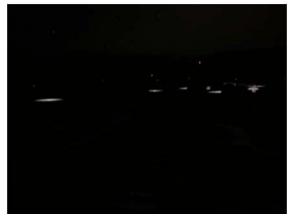
Clone Mode 2

In Clone Mode 2, the IG generates a normal high-dynamic range visible dark night scene, which is directly applied to the AVIOR[®] Vis laser. That same video signal undergoes a basic power law "gamma" transformation and is applied to the AVIOR[®] IR laser for NVG stimulation.

The gamma modification amplifies the lowest light levels relatively more than the medium or high brightness levels. The extremely dark parts of the scene projected with the AVIOR[®] IR l aser projector are r ealistic in the go ggles. Brighter objects or artificial lights induce blooming in the goggles. The specific g amma f unction u sed is tu ned to assure that dither no ise associated with the high dynamic range video input is not objectionable in the goggles.



(a) Scenario in daylight



(b) Scenario at night



(c) Scenario observed through NVG

Figure 3 Scenario with urban terrain generated with VITAL X fro mission training in a simulator using Clone Mode 2.

NVG STIMULATION IN A SIMULATED WORLD

Clone Mode 2 operation of the VITAL X image generator and t he AVIOR[®]VisIR l aser p rojector i s sh own in the following pictures of a helicopter mission in Afghanistan. The i mages were directly ph otographed from t he projection screen. Figures 3 to 5 show the scenario first in day t ime, second in the visible ni ght s cene which i s o f course mostly b lack, and at l ast i n t he N V i mage photographed through the goggles.

Figure 3 shows urban t errain containing many a rtificial lights, which are seen at full intensity in the unaided view and which generate strong NV effects in the NVG.

Figure 4 shows an AVIOR[®]VisIR scenario with buildings near an airfield. At night these buildings are well-lit and generate strong NV effects and blending in the NVG.

Finally, Figure 5 presents non -urban ar ea s cenario i n a strong dark environment. In this environment, the terrain is dark a t ni ght a nd o nly t he b urning o bject c ould b e s een visually. T he N VG i mage s hows a ll t he d etails o f th e terrain a nd t he b looming i mage o f t he b right, b urning object.

CONCLUSION

The A VIOR[®]VisIR l aser p rojection sy stem p rovides t he following fundamental benefits:

- The addition of an internal IR laser allows fully independent control of the visible and stimulated NVG p resentations al lowing an i deal b alance of visible s cene ill umination a nd N VG s timulation to be achieved.
- The intrinsic laser black level approaches that of CRTs thus p roviding r ealistic ni ght scene b lack levels. The I R l aser a lso h as in trinsically high contrast, which enhances the NVG image.
- The 8 30 nm I R laser frequency e nhances N VG stimulation across goggle types.
- The optional Clone Mode reduces cost while retaining high-quality stimulation.
- High le vels o f stimulation inherently p rovide realistic goggle blooming.

The d escribed vi sual system with the V ITAL X i mage generator and the AVIOR[®]VisIR laser projection system is

a unique, very high quality N VG stimulation facility for optimized training of aircrews us ing their original NVG equipment in a simulated world.



(a) Scenario in daylight



(b) Scenario at night



(c) Scenario observed through NVG

Figure 4 Scenario near an airfield with well-lit buildings generated with VITAL X for mission training in a simulator.



(a) Scenario in daylight



(b) Scenario at night



(c) Scenario observed through NVG

Figure 5 Scenario in a non-urban area generated with VITAL X for mission training in a simulator.

ABOUT THE AUTHORS

Dr. Hubert Burggraf is V ice President and Head of the division D isplay and L aser S ystems in the b usiness unit Simulation a nd T raining a t R heinmetall D efence Electronics GmbH in Bremen, Germany. He has for more than 25 years experience in the areas of laser development, laser-optical sensors, optical signal processing, laser-based combat simulation, v isual s ystems, P C-based i mage generators, la ser p rojection s ystems a nd n ight v ision simulation. H e pu blished/holds a set of papers/patents in these fields.

Dr. Wilfried Plass has now 1 0 y ears of e xperience a s display s ystem engineer w ithin the f light s imulation department at Rheinmetall Defence Electronics GmbH in Bremen, mainly a ccompanying t he i ntroduction of t he AVIOR[®] laser p rojection s ystem i nto f light s imulation displays. H e g raduated in physics a t th e U niversity of Bielefeld, G ermany, a nd r eceived an e ngineering P hD from t he U niversity o f S tuttgart, G ermany, mainly working on high power optics and ultra short laser pulses.

Dr. Charles J. Lloyd has 2.3 y ears of experience in the area of display systems and applied vision research at such organizations as the Displays and Controls Lab at Virginia Tech, t he A dvanced D isplays G roup at H oneywell, Lighting R esearch Center at Rensselaer P olytech, V isual Performance I nc., an d B ARCO P rojection S ystems. Charles now works at FlightSafety International where he manages the d evelopment of next-generation d isplay a nd alignment systems. Charles has published/presented more than 50 papers in the field.

Steven G. Nigus is Director of Engineering for the Visual Simulation Systems division of FlightSafety International in St. Louis, MO. He has been designing visual systems for 25 years and has performed various system design and engineering management functions in the development of the VITAL 7, 8, 9, and X visual system generations. Mr. Nigus is currently managing FlightSafety's visual system hardware, software, and di splay product engineering activities. He received h is bachelor's degree in electrical engineering from the University of Missouri at Rolla and did his graduate work at Iowa State University. Steve has published 12 conference papers on visual simulation.

Brian K. Ford is a Lead R ealtime Software Engineer at FlightSafety International Visual Simulation Systems. For the p ast 1 1 years, h e h as b een d esigning s ystems architecture and network communications for VITAL 8, 9 and X visual systems, as well as sensor features including video t arget tracking. He is currently designing the VITAL 9 and X C DB publisher in tegrations. P reviously,

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he spent 5 years at the University of Missouri's Advanced Technology Center applying virtual reality and multimedia for us e in e lementary, secondary, a nd u ndergraduate education. H e r eceived B achelor of S cience d egrees in both E lectrical an d C omputer E ngineering f rom t he University of Missouri, Columbia.

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